

MicroC/OS-II Chapter 7

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CHAPTER 7 Semaphore Management

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Ch7

Semaphore Management

A semaphore

- allows a task to synchronize with either an ISR or a task
(you initialize the semaphore to 0)
- gains exclusive access to a resource
(you initialize the semaphore to a value greater than 0)
- signals the occurrence of an event
(you initialize the semaphore to 0)

Table 7.1

Semaphore configuration constants in OS_CFG.H

μ C/OS-II Semaphore Service	Enabled when set to 1 in S_CFH.H
OSSemAccept()	OS_SEM_ACCEPT_EN
OSSemCreate()	
OSSemDel()	OS_SEM_DEL
OSSemPend()	
OSSemPost()	
OSSemQuery()	OS_SEM_QUERY_EN

7.00 Creating a Semaphore, [OSSemCreate()]

- You create a semaphore by calling OSSemCreate() and specifying the initial count of the semaphore.
- The initial value of a semaphore can be between 0 and 65,536
- If you use the semaphore to signal the occurrence of one or more events, you initialize the semaphore to 0
- If you use the semaphore to access a single shared resource, you need to initialize the semaphore to 1
- If the semaphore allows your application to obtain any one of n identical resources, initialize the semaphore to n and use it as a counting semaphore

Listing 7.1 Creating a Semaphore,[OSSemCreate]

```
OS_EVENT *OSSemCreate (INT16U cnt)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR cpu_sr;
#endif

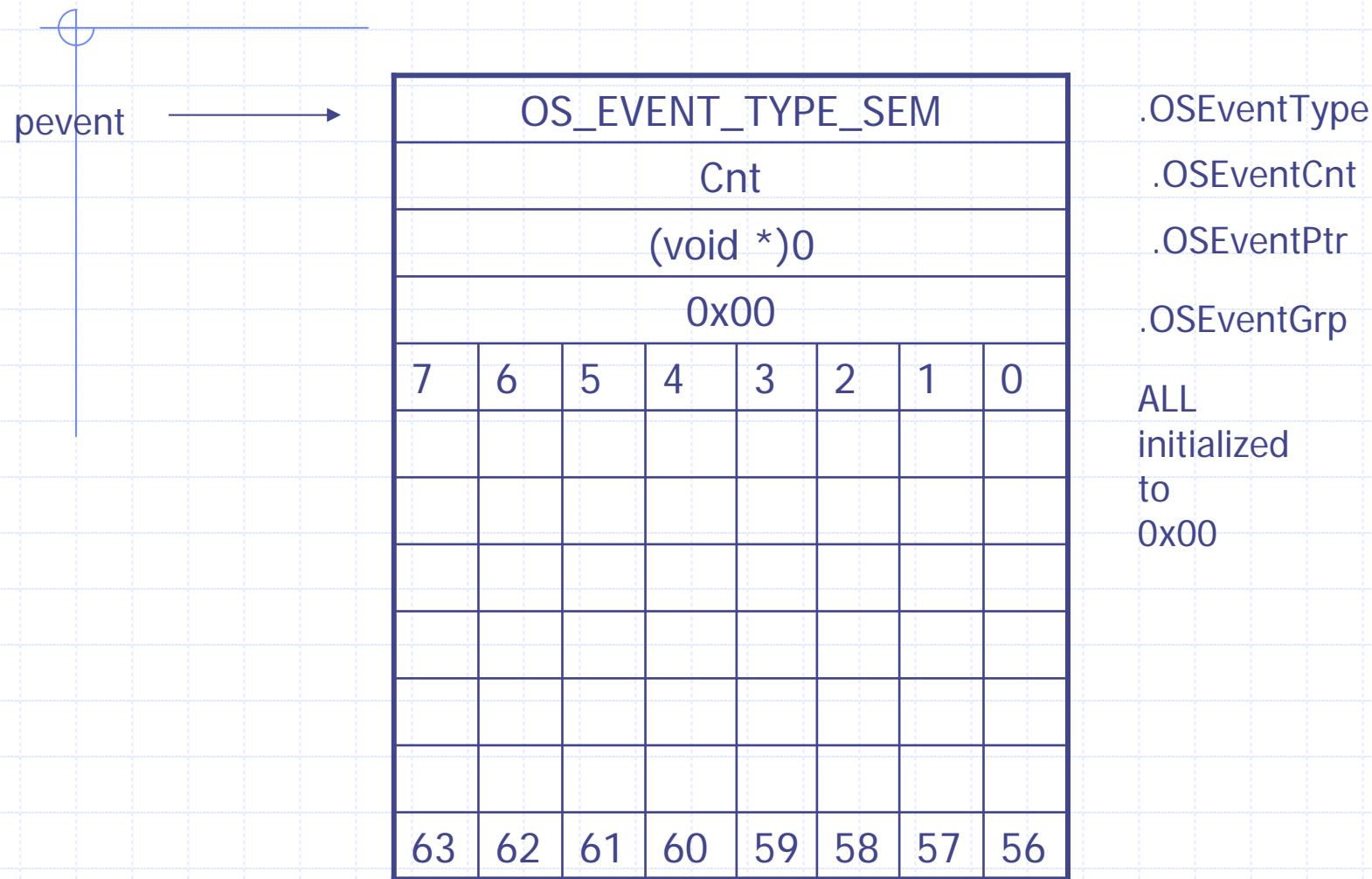
    OS_EVENT *pevent;

    if (OSIntNesting > 0) {
        return ((OS_EVENT *)0);
    }
    OS_ENTER_CRITICAL();
    pevent = OSEventFreeList;
    if (OSEventFreeList != (OS_EVENT *)0) {
        OSEventFreeList = (OS_EVENT *)OSEventFreeList->OSEventPtr;
    }
    OS_EXIT_CRITICAL();
}
```

Listing 7.1 Creating a Semaphore,[OSSemCreate]

```
if (pevent != (OS_EVENT *)0) {  
    pevent->OSEventType = OS_EVENT_TYPE_SEM;  
    pevent->OSEventCnt = cnt;  
    pevent->OSEventPtr = (void *)0;  
    OS_EventWaitListInit(pevent);  
}  
return (pevent);  
}
```

Figure 7.2 ECB just before OSSemCreate() returns.



7.01 Deleting a Semaphore,[OSSemDel()]

- OSSemDel() is used to delete a semaphore.
- This function is dangerous to use because multiple tasks could attempt to access a deleted semaphore.
- Before you delete a semaphore, you must first delete all the tasks that can access the semaphore.

Notes :

- Interrupts are disabled when pended tasks are readied, which means that interrupt latency depends on the number of task that are waiting on the semaphore.

Listing 7.2 Deleting a Semaphore, [OSSemDel()]

```
OS_EVENT *OSSemDel (OS_EVENT *pevent, INT8U opt, INT8U *err)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR cpu_sr;
#endif

    BOOLEAN tasks_waiting;
    if (OSIntNesting > 0) {
        *err = OS_ERR_DEL_ISR;
        return (pevent);
    }

#if OS_ARG_CHK_EN > 0
    if (pevent == (OS_EVENT *)0) {
        *err = OS_ERR_PEVENT_NULL;
        return (pevent);
    }
    if (pevent->OSEventType != OS_EVENT_TYPE_SEM) {
        *err = OS_ERR_EVENT_TYPE;
        return (pevent);
    }
#endif
}
```

Listing 7.2 Deleting a Semaphore, [OSSemDel()]

```
OS_ENTER_CRITICAL();

if (pevent->OSEventGrp != 0x00) {

    tasks_waiting = TRUE;

} else {

    tasks_waiting = FALSE;

}

switch (opt) {

case OS_DEL_NO_PEND:

    if (tasks_waiting == FALSE) {

        pevent->OSEventType = OS_EVENT_TYPE_UNUSED;

        pevent->OSEventPtr = OSEventFreeList;

        OSEventFreeList = pevent;

        OS_EXIT_CRITICAL();

        *err = OS_NO_ERR;

        return ((OS_EVENT *)0);

    }

}
```

Listing7.2 Deleting a Semaphore, [OSSemDel()]

```
    else {
        OS_EXIT_CRITICAL();
        *err = OS_ERR_TASK_WAITING;
        return (pevent);
    }

case OS_DEL_ALWAYS:
    while (pevent->OSEventGrp != 0x00) {
        OS_EventTaskRdy(pevent, (void *)0, OS_STAT_SEM);
    }

    pevent->OSEventType = OS_EVENT_TYPE_UNUSED;
    pevent->OSEventPtr = OSEventFreeList;
    OSEventFreeList = pevent;
    OS_EXIT_CRITICAL();
```

Listing7.2 Deleting a Semaphore, [OSSemDel()]

```
if (tasks_waiting == TRUE) {  
    OS_Sched();  
}  
  
*err = OS_NO_ERR;  
return ((OS_EVENT *)0);  
  
default:  
    OS_EXIT_CRITICAL();  
    *err = OS_ERR_INVALID_OPT;  
    return (pevent);  
}  
}
```

7.02 Waiting on a Semaphore, [OSSemPend()]

- OSSemPend() is used when task want **exclusive access** to a resource, needs to **synchronize its activities** with an ISR or a task, or is **waiting until an event occurs**.
- If a task calls OSSemPend() and the value of the semaphore is **greater than 0**, OSSemPend() decrements the semaphore and returns to its caller.
- If the values of the semaphore **is 0**, OSSemPend() places the calling task **in the waiting list** for the semaphore.
- The **task waits until a task or an ISR signals the semaphore or the specified timeout expires**.
- If the **semaphore is signal**, μ C/OS-II resumes **the highest priority task** waiting for the semaphore

Listing 7.3 Waiting on a Semaphore, [OSSemPend()]

```
void OSSemPend (OS_EVENT *pevent, INT16U timeout, INT8U *err)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR  cpu_sr;
#endif

    if (OSIntNesting > 0) {                                /* See if called from ISR ... */
        *err = OS_ERR_PEND_ISR;                            /* ... can't PEND from an ISR */
        return;
#endif OS_ARG_CHK_EN > 0
    if (pevent == (OS_EVENT *)0) {
        *err = OS_ERR_PEVENT_NULL;
        return (pevent);
    }
    if (pevent->OSEventType != OS_EVENT_TYPE_SEM) {
        *err = OS_ERR_EVENT_TYPE;
        return (pevent);
    }
#endif
```

Listing 7.3 Waiting on a Semaphore, [OSSemPend()]

```
OS_ENTER_CRITICAL();

    if (pevent->OSEventCnt > 0) {
        pevent->OSEventCnt--;
        OS_EXIT_CRITICAL();
        *err = OS_NO_ERR;
        return;
    }
    OSTCBCur->OSTCBStat |= OS_STAT_SEM;
    OSTCBCur->OSTCBDly = timeout;
    OS_EventTaskWait(pevent);
    OS_EXIT_CRITICAL();
    OS_Sched();                                /* Find next highest priority
                                                task ready */

    OS_ENTER_CRITICAL();
    if (OSTCBCur->OSTCBStat & OS_STAT_SEM) {
        OS_EventT0(pevent);
        OS_EXIT_CRITICAL();
        *err = OS_TIMEOUT;
        return;
    }
```

Listing 7.3 Waiting on a Semaphore, [OSSemPend()]

```
OSTCBCur->OSTCBEventPtr = (OS_EVENT *)0;  
OS_EXIT_CRITICAL();  
*err = OS_NO_ERR;  
}
```

7.03 Signaling on a Semaphore, [OSSemPost()]

- A semaphore is signaled by calling OSSemPost().
- If the semaphore value is 0 or more, it is incremented.
- If the task are waiting for the semaphore to be signaled, OSSemPost() removes the highest priority task from the waiting list and make this task ready to run

Listing 7.4 Signaling on a Semaphore, [OSSemPend()]

```
INT8U OSSemPost (OS_EVENT *pevent)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR  cpu_sr;
#endif

#if OS_ARG_CHK_EN > 0
    if (pevent == (OS_EVENT *)0) {                                /* Validate 'pevent' */
        return (OS_ERR_PEVENT_NULL);
    }
    if (pevent->OSEventType != OS_EVENT_TYPE_SEM) {            /* Validate event block type
*/}
        return (OS_ERR_EVENT_TYPE);
    }
#endif

    OS_ENTER_CRITICAL();
    if (pevent->OSEventGrp != 0x00) {
        OS_EventTaskRdy(pevent, (void *)0, OS_STAT_SEM);
    }
    OS_EXIT_CRITICAL();
    OS_Sched();
    return (OS_NO_ERR);
}
```

Listing 7.4 Signaling on a Semaphore, [OSSemPend()]

```
if (pevent->OSEventCnt < 65535) {  
    pevent->OSEventCnt++;  
    OS_EXIT_CRITICAL();  
    return (OS_NO_ERR);  
}  
OS_EXIT_CRITICAL();  
return (OS_SEM_OVF);  
}
```

7.04,

Getting a Semaphore Without Waiting, [OSSemAccept()]

- OSSemAccept() checks to see if a resource is available or an event has occurred.
- But it does not suspend the calling task if the resource is not available.

Example

```
OS_EVENT *DispSem;

Void Task (void *pdata)
{
    INT16U value;
    pdata =pdata;
    for(;;){
        value =OSSemAccept(DispSem);
        if (value > 0){           /*Resource available, process..*/
            }
        ...
    }
}
```

Listing 7.5

Getting a Semaphore Without Waiting, [OSSemAccept()]

```
INT16U OSSemAccept (OS_EVENT *pevent)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR  cpu_sr;
#endif
    INT16U      cnt;
#if OS_ARG_CHK_EN > 0
    if (pevent == (OS_EVENT *)0) {
        return (0);
    }
    if (pevent->OSEventType != OS_EVENT_TYPE_SEM) {
        return (0);
    }
#endif
```

List 7.5 Getting a Semaphore Without Waiting, [OSSemAccept()]

```
OS_ENTER_CRITICAL();
cnt = pevent->OSEventCnt;
if (cnt > 0){
    pevent->OSEventCnt--;
}
OS_EXIT_CRITICAL();
return (cnt);
}
```

7.05

Obtaining the Status of a Semaphore, [OSSemQuery]

- OSSemQuery() receives tow arguments :
pEvent contains a pointer to the semaphore.
pdata is a pointer to a data structure (OS_SEM_DATA) that hold information about the semaphore.

pdata: contains the following fields

INT16U OSCnt;

INT8U OSEventTbl[OS_EVENT_TBL_SIZE];

INT8U OSEventGrp;

Listing 7.6

Obtaining the Status of a Semaphore, [OSSemQuery]

```
INT8U OSSemQuery (OS_EVENT *pevent, OS_SEM_DATA *pdata)
{
    #if OS_CRITICAL_METHOD == 3
        OS_CPU_SR  cpu_sr;
    #endif
    INT8U      *psrc;
    INT8U      *pdest;

#if OS_ARG_CHK_EN > 0
    if (pevent == (OS_EVENT *)0) {                                /* Validate 'pevent' */
        return (OS_ERR_PEVENT_NULL);
    }
    if (pevent->OSEventType != OS_EVENT_TYPE_SEM) {
        return (OS_ERR_EVENT_TYPE);
    }
#endif
```

Listing 7.6

Obtaining the Status of a Semaphore, [OSSemQuery]

```
OS_ENTER_CRITICAL();

    pdata->OSEventGrp = pevent->OSEventGrp;
    pdest              = &pdata->OSEventTbl[0];

#if OS_EVENT_TBL_SIZE > 0
    *pdest++          = *psrc++;
#endif

#if OS_EVENT_TBL_SIZE > 1
    *pdest++          = *psrc++;
#endif

#if OS_EVENT_TBL_SIZE > 2
    *pdest++          = *psrc++;
#endif
```

Listing 7.6

Obtaining the Status of a Semaphore, [OSSemQuery]

```
#if OS_EVENT_TBL_SIZE > 3
    *pdest++      = *psrc++;
#endif

#if OS_EVENT_TBL_SIZE > 4
    *pdest++      = *psrc++;
#endif

#if OS_EVENT_TBL_SIZE > 5
    *pdest++      = *psrc++;
#endif
#if OS_EVENT_TBL_SIZE > 6
    *pdest++      = *psrc++;
#endif
#if OS_EVENT_TBL_SIZE > 7
    *pdest        = *psrc;
#endif

pdata->OSCnt      = pevent->OSEventCnt;
OS_EXIT_CRITICAL();

return (OS_NO_ERR);
}
```