

ch5

Time Management

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Speaker:Ming-Shyong Tsai

Clock Tick

- Periodic interrupt
 - Keep track of time delays and timeouts
 - clock ticks : 10 ~ 100 Hz
- five services deal with time issues:
 - OSTimeDly() *Enable when set to 1 in OS_CFG.h*
 - OSTimeDlyHMSM() *OS_TIME_DLY_HMSM_EN*
 - OSTimeDlyResume() *OS_TIME_DLY_RESUME_EN*
 - OSTimeGet() *OS_TIME_DLY_GET_SET_EN*
 - OSTimeSet() *OS_TIME_DLY_GET_SET_EN*

OSTimeDly(1/3)

```
void OSTimeDly (INT16U ticks)
{
    if (ticks > 0) {
        OS_ENTER_CRITICAL();

        if ((OSRdyTbl[OSTCBCur->OSTCBY]
            &= ~OSTCBCur->OSTCBBitX) == 0)
            OSRdyGrp &= ~OSTCBCur->OSTCBBitY;
    }
    OSTCBCur->OSTCBDly = ticks;
    OS_EXIT_CRITICAL();
    OSSched();
}
```

OSTimeDly(2/3)

- **OSRdyTbl []**
 - Table of tasks which are ready to run
- **OSTCBY**
 - Index into ready table corresponding to task priority
- **OSTCBBitX**
 - Bit mask to access bit position in ready table
- **OSRdyGrp**
 - Ready list group
- **OSTCBBitY**
 - Bit mask to access bit position in ready group

OSTimeDly(3/3)

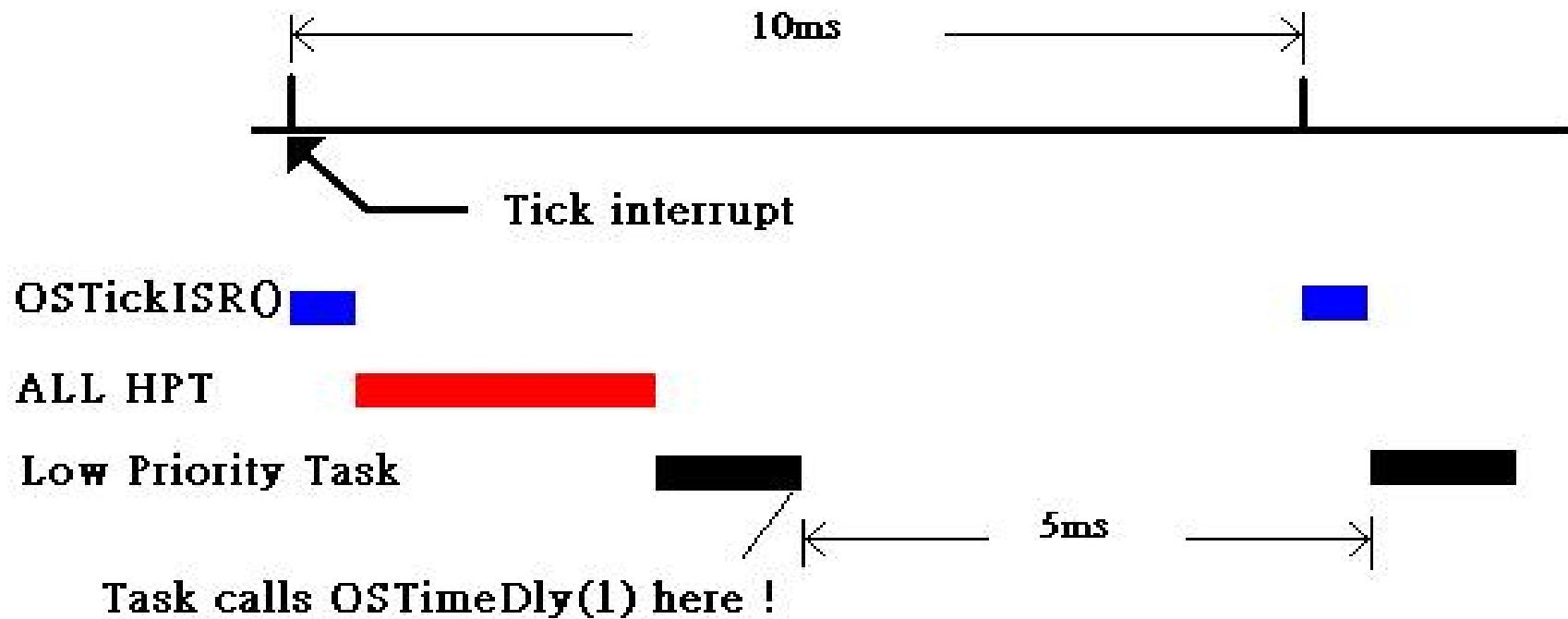


Figure 1. Delay resolution

OSTimeDlyHMSM

```
INT8U OSTimeDlyHMSM (INT8U hours,
                      INT8U minutes, INT8U seconds, INT16U
                      milli)
{
    INT32U ticks;
    INT16U loops;

    if (hours > 0 || minutes > 0 || seconds > 0
        || milli > 0) {
        if (minutes > 59) {
            return(OS_TIME_INVALID_MINUTES);
        }
        if (seconds > 59) {
            return(OS_TIME_INVALID_SECONDS);
        }
        if (milli > 999) {
            return (OS_TIME_INVALID_MILLI);
        }
    }

    ticks = (INT32U) hours * 3600L *
            OS_TICKS_PER_SEC
    + (INT32U) minutes * 60L *
            OS_TICKS_PER_SEC
    + (INT32U) seconds *
            OS_TICKS_PER_SEC
    + OS_TICKS_PER_SEC *
        ((INT32U) milli + 500L /
        OS_TICKS_PER_SEC ) / 1000L;
    loops = ticks / 65536L;
    ticks = ticks % 65536L;
    OSTimeDly(ticks);
    while (loops > 0) {
        OSTimeDly(32768);
        OSTimeDly(32768);
        loops--;
    }
    return (OS_NO_ERR);
} else {
    return (OS_TIME_ZERO_DLY);
}
```

OSTimeDlyResume(1/2)

- Delayed tasks
 - Timeout
 - Be awaked by another tasks
 - OSTimeDlyResume() can also resume a task waiting for an event
- The task need to satisfy
 - a valid priority
 - existence
 - If the task exists ,It is waiting for delayed time to expire
 - Not suspended

Then the task can be placed in ready list
- A task maybe delays itself by semaphore, mutex, event flag, mailbox, queue . And It can resume itself by the same way but requires more RAM for the ECB(event control block)

OSTimeDlyResume(2/2)

```
INT8U OSTimeDlyResume (INT8U prio)
{
    OS_TCB *ptcb;

    if (prio >= OS_LOWEST_PRIO) {
        return (OS_PRIO_INVALID);
    }

    OS_ENTER_CRITICAL();

    ptcb = (OS_TCB *)OSTCBPrioTbl[prio];
    if (ptcb != (OS_TCB *)0) {
        if (ptcb->OSTCBDly != 0) {
            ptcb->OSTCBDly = 0;
        }

        if (!(ptcb->OSTCBStat
              & OS_STAT_SUSPEND)) {
            OSRdyGrp |= ptcb->OSTCBBitY;
            OSRdyTbl[ptcb->OSTCBY] |=
                ptcb->OSTCBBitX;
        }
    }
    OS_EXIT_CRITICAL();
    OSSched();
} else {
    OS_EXIT_CRITICAL();
}
return (OS_NO_ERR);
} else {
    OS_EXIT_CRITICAL();
    return (OS_TIME_NOT_DLY);
}
} else {
    OS_EXIT_CRITICAL();
    return (OS_TASK_NOT_EXIST);
}
}
```

System time, OSTimeGet and OSTimeSet(1/2)

- μC/ OSII : 32 bit-counter
 - Start at zero
 - increment itself when clock tick occurs
 - Multitasking by calling OSStart()
 - Obtain the current value by OSTimeGet()
 - Change the value by OSTimeSet()
- When accessing OSTime, interrupts are disabled
 - the most 8-bit processor ,32-bit counter
 - counter ++
 - copy a 32-bit value
 - atomic instruction

System time, OSTimeGet and OSTimeSet(2/2)

```
INT32U OSTimeGet (void)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR cpu_sr;
#endif
    INT32U ticks;

    OS_ENTER_CRITICAL();
ticks = OSTime;
    OS_EXIT_CRITICAL();
    return (ticks);
}
```

```
void OSTimeSet (INT32U ticks)
{
#if OS_CRITICAL_METHOD == 3
    OS_CPU_SR cpu_sr;
#endif
    OS_ENTER_CRITICAL();
OSTime = ticks;
    OS_EXIT_CRITICAL();
}
```